Growth rates of permutation grid classes, tours on graphs, and the spectral radius

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Abstract

Monotone grid classes of permutations have proven very effective in helping to determine structural and enumerative properties of classical permutation pattern classes. Associated with grid class \( \text{Grid}(M) \) is a graph, \( G(M) \), known as its “row-column” graph. We prove that the exponential growth rate of \( \text{Grid}(M) \) is equal to the square of the spectral radius of \( G(M) \). Consequently, we utilize spectral graph theoretic results to characterise all slowly growing grid classes and to show that for every \( \gamma \geq 2 + \sqrt{5} \) there is a grid class with growth rate arbitrarily close to \( \gamma \). To prove our main result, we establish bounds on the size of certain families of tours on graphs. In the process, we prove that the family of tours of even length on a connected graph grows at the same rate as the family of “balanced” tours on the graph (in which the number of times an edge is traversed in one direction is the same as the number of times it is traversed in the other direction).

1 Introduction

We consider a permutation to be simply an arrangement of the numbers 1, 2, \ldots, k for some positive k. We use \(|\sigma|\) to denote the length of permutation \( \sigma \). A permutation \( \tau \) is said to be contained in, or to be a subpermutation of, another permutation \( \sigma \) if \( \sigma \) has a subsequence whose terms have the same relative ordering as \( \tau \). It can be helpful to consider permutations graphically, and from the graphical perspective, \( \sigma \) contains \( \tau \) if the plot of \( \tau \) results from erasing some points from the plot of \( \sigma \) and then “shrinking” the axes appropriately. If \( \sigma \) does not contain \( \tau \), we say that \( \sigma \) avoids \( \tau \). For example, 31567482 contains 1324 (see Figure 1) but avoids 1243.

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The containment relation is a partial order on the set of all permutations. A classical permutation class (or “pattern class”) is a set of permutations closed downwards (a down-set) in this partial order. From a graphical perspective, this means that erasing points from the plot of a permutation in a permutation class $C$ always results in the plot of another permutation in $C$ when the axes are rescaled appropriately.

Given a permutation class $C$, we denote by $C_k = \{ \sigma \in C : |\sigma| = k \}$ the set of permutations in $C$ of length $k$. The (ordinary) generating function of $C$ is thus $\sum_{k \in \mathbb{N}} |C_k| z^k = \sum_{\sigma \in C} z^{|\sigma|}$.

It is common to define a permutation class $C$ “negatively” by stating the minimal set of permutations $B$ that do not occur in the class. In this case, we write $C = \operatorname{Av}(B)$ (where $\operatorname{Av}$ signifies “avoids”). $B$ is called the basis of $C$. The basis of a permutation class is an antichain (a set of pairwise incomparable elements) and may be infinite.

The monotone grid class $\operatorname{Grid}(M)$ is a permutation class defined by a matrix $M$, all of whose entries are in $\{0, 1, -1\}$, which specifies the acceptable “shape” for plots of permutations in the class. Each entry of $M$ corresponds to a cell in a “gridding” of a permutation. If the entry is 1, any points in the cell must form an increasing sequence; if the entry is $-1$, any points in the cell must form a decreasing sequence; if the entry is 0, the cell must be empty. For greater clarity, we denote grid classes by cell diagrams rather than by their matrices; for example, $\begin{array}{ll}
\begin{array}{ll}
\begin{array}{ll}
\begin{array}{ll}
\begin{array}{ll}
\end{array}
\end{array}
\end{array}
\end{array}
\end{array}$ = $\operatorname{Grid}(\begin{array}{ll}
\begin{array}{ll}
\begin{array}{ll}
\begin{array}{ll}
1 & -1 \\
0 & 0 \\
-1 & 1
\end{array}
\end{array}
\end{array})$. A permutation may have multiple possible griddings in a grid class (see Figure 2 for an example).

Recent years have seen much progress on understanding enumerative and structural properties of permutation classes. The use of grid classes has proven particularly fruitful. One focus of research has been the enumeration of permutation classes that have small bases (see [32]). In this context the first use of grid classes (but not using that term) was by Atkinson [7], who determined that

$$\operatorname{Av}(132, 4321) = \begin{array}{ll}
\begin{array}{ll}
\begin{array}{ll}
\begin{array}{ll}
\end{array},
\end{array}
\end{array}
\end{array} \cup \begin{array}{ll}
\begin{array}{ll}
\begin{array}{ll}
\begin{array}{ll}
\end{array}
\end{array}
\end{array}
\end{array}.$$
and used the fact to enumerate this class of permutations. More recently, Albert, Atkinson and Brignall [1, 2] and Albert, Atkinson and Vatter [5] have demonstrated the practical uses of grid classes for permutation class enumeration by determining the generating functions of seven permutation classes whose bases consist of two permutations of length four.

Another primary area of exploration has concerned the growth rates of permutation classes. Marcus and Tardos [22] proved the conjecture of Stanley and Wilf that for any permutation class $\mathcal{C}$ except the class of all permutations there exists a constant $c$ such that $|\mathcal{C}_{k}| \leq c^k$ for all $k$. Thus, every permutation class with non-empty basis has finite lower and upper exponential growth rates defined, respectively, by

$$\text{gr}(\mathcal{C}) = \liminf_{k \to \infty} |\mathcal{C}_{k}|^{1/k} \quad \text{and} \quad \text{gr}^{\uparrow}(\mathcal{C}) = \limsup_{k \to \infty} |\mathcal{C}_{k}|^{1/k}.$$ 

If the lower and upper growth rates coincide, then $\mathcal{C}$ has a growth rate, which we denote $\text{gr}(\mathcal{C})$. (It is widely conjectured that every permutation class has a growth rate.) In [30], Vatter investigated the possible values of permutation class growth rates, and used generalised grid classes to characterize all the (countably many) permutation classes with growth rates below $\kappa \approx 2.0557$. He also established that there are uncountably many permutation classes with growth rate $\kappa$, and in a separate paper [29], showed that there are permutation classes having every growth rate above $\lambda \approx 2.48188$. (The behaviour between $\kappa$ and $\lambda$ is the subject of ongoing research.)

Grid classes have also been a subject of investigation themselves. The first to be studied was the class of skew-merged permutations $\mathcal{G}$. Stankova [28] and Kédzy, Snevily and Wang [19] proved that this class is $\text{Av}(2143, 3412)$, and Atkinson [6] determined its generating function. More recently, Waton, in his PhD thesis [31], enumerated $\mathcal{G}$. In addition to these enumerations, some structural results have also been established. Atkinson [7] proved that grid classes whose matrices have dimension $1 \times m$ have a finite basis. Waton [31] proved the same for $\mathcal{G}$, a result which has been extended by Albert, Atkinson and Brignall [3] to all $2 \times 2$ grid classes. (It is generally believed that all grid classes have a finite basis, but this has not yet been proven; see [18] Conjecture 2.3.)

Associated with each grid class is a bipartite graph known as its “row-column” graph, which encapsulates certain structural information about the class. (We present its definition later in Section 3.) Particularly of note, Murphy and Vatter [23] have shown that a grid class is partially well-ordered (contains no infinite antichains) if and only if its row-column graph has no cycles. Moreover, Albert, Atkinson, Bouvel, Ruškuc and Vatter [4] proved a result that implies that if a grid class has an acyclic row-column graph then the generating function of the class is a rational function (the ratio of two polynomials).

Our focus in this paper is on the growth rates of grid classes. We prove the following theorem:

**Theorem 3.6.** The growth rate of a monotone grid class of permutations exists and is equal to the square of the spectral radius of its row-column graph.
The bulk of the work required to prove this theorem is concerned with carefully counting certain families of tours on graphs, in order to give bounds on their sizes. In particular, we consider “balanced” tours, in which the number of times an edge is traversed in one direction is the same as the number of times it is traversed in the other direction. As a consequence, we prove the following new result concerning tours on graphs:

**Theorem 2.8.** The growth rate of the family of balanced tours on a connected graph is the same as that of the family of all tours of even length on the graph.

As a consequence of Theorem 3.6, by using the machinery of spectral graph theory, we are able to deduce a variety of supplementary results. We give a characterisation of grid classes whose growth rates are no greater than $\frac{9}{2}$ (in a similar fashion to Vatter’s characterisation of “small” permutation classes in [30]). We also fully characterise all accumulation points of grid class growth rates, the least of which occurs at 4. Other results include:

**Corollary 4.1.** The growth rate of every monotone grid class is an algebraic integer.

**Corollary 4.3.** A monotone grid class whose row-column graph is a cycle has growth rate 4.

**Corollary 4.5.** If the growth rate of a monotone grid class is less than 4, it is equal to $4 \cos^2(\frac{\pi}{k})$ for some $k \geq 3$.

**Corollary 4.10.** For every $\gamma \geq 2 + \sqrt{5}$ there is a monotone grid class with growth rate arbitrarily close to $\gamma$.

The remainder of this paper is structured as follows: In Section 2, we introduce the particular families of tours on graphs that we study and present our results concerning these tours, culminating in the proof of Theorem 2.8. This is followed, in Section 3, by the application of these results to prove our grid class growth rate result, Theorem 3.6. Section 4, contains a number of consequences of Theorem 3.6 that follow from known spectral graph theoretic results. We conclude with a few final remarks.

## 2 Tours on graphs

In this section, we investigate families of tours on graphs, parameterised by the number of times each edge is traversed. We determine a lower bound on the size of families of “balanced” tours and an upper bound on families of arbitrary tours. Applying the upper bound to tours of even length gives us an expression compatible with the lower bound. Combining this with the fact that any balanced tour has even length enables us to prove Theorem 2.8 which reveals that even-length tours and balanced tours grow at the same rate. These bounds are subsequently used in Section 3 to relate tours on graphs to permutation grid classes.
To establish the lower and upper bounds, we first enumerate tours on trees. We then present a way of associating tours on an arbitrary connected graph $G$ with tours on a related “partial covering” tree, which we employ to determine bounds for families of tours on arbitrary graphs. Let us begin by introducing the tours that we will be considering.

### 2.1 Notation and definitions

A *walk*, of length $k$, on a graph is a non-empty alternating sequence of vertices and edges $v_0, e_1, v_1, e_2, v_2, \ldots, e_k, v_k$ in which the endvertices of $e_i$ are $v_{i-1}$ and $v_i$. Neither the edges nor the vertices need be distinct. We say that such a walk traverses edges $\{e_1, \ldots, e_k\}$ and visits vertices $\{v_1, \ldots, v_{k-1}\}$. A *tour* (or *closed walk*) is a walk which starts and ends at the same vertex (i.e. $v_k = v_0$). Our interest is restricted to tours.

In what follows, when considering a graph with $m$ edges, we denote its edges $e_1, e_2, \ldots, e_m$. In any particular context, we can choose the ordering of the edges so as to simplify our presentation. We denote the edges incident to a given vertex $v$ by $e_1^v, e_2^v, \ldots, e_{d(v)}^v$, where $d(v)$ is the *degree* of $v$ (number of edges incident to $v$). Again, we are free to choose the order of the edges incident to a vertex so as to clarify our arguments.

**Families of tours**

Our interest is in families of tours that are parameterised by the number of times each edge is traversed. Given non-negative integers $h_1, h_2, \ldots, h_m$ and some vertex $u$ of a graph $G$, we use

$$W_G((h_i); u) = W_G(h_1, h_2, \ldots, h_m; u)$$

to denote the family of tours on $G$ which start and end at $u$ and traverse each edge $e_i$ exactly $h_i$ times. (We use $W$ rather than $T$ for families of tours to avoid confusion when considering tours on trees.)

We use $h_1^v, h_2^v, \ldots, h_{d(v)}^v$ for the number of traversals of edges incident to a vertex $v$ in $W_G((h_i); u)$. So, if $v$ and $w$ are the endvertices of $e_i$, $h_i$ has two aliases $h_j^v$ and $h_j^w$ for some $j$ and $j'$.

We use $W_G((h_i); u) = |W_G((h_i); u)|$ to denote the number of these tours.

Note that for some values of $h_1, \ldots, h_m$, the family $W_G((h_i); u)$ is empty. In particular, if $E^+ = \{e_i \in E(G) : h_i > 0\}$ is the set of edges visited by tours in the family, and $G^+ = G[E^+]$ is the subgraph of $G$ induced by these edges, then if $G^+$ is disconnected or does not contain $u$, we have $W_G((h_i); u) = \emptyset$. A family of tours may also be empty for “parity” reasons; for example, if $T$ is a tree, then $W_T((h_i); u) = \emptyset$ if any of the $h_i$ are odd. Our counting arguments must remain valid for these empty families.
Of particular interest to us are tours in which the number of times an edge is traversed in one direction is the same as the number of times it is traversed in the other direction. We call such tours balanced.

Given non-negative integers $k_1, k_2, \ldots, k_m$ and some vertex $u$ of a graph $G$, we use $W^b_G((k_i); u) = W^b_G(k_1, k_2, \ldots, k_m; u)$ to denote the family of balanced tours on $G$ which start and end at $u$, and traverse each edge $e_i$ exactly $k_i$ times in each direction. Note that we parameterise balanced tours by half the number of traversals of each edge.

We use $k^v_1, k^v_2, \ldots, k^v_{d(v)}$ for the number of traversals in either direction of edges incident to a vertex $v$ in $W^b_G((k_i); u)$. So, if $v$ and $w$ are the endvertices of $e_i$, $k_i$ has two aliases $k^v_j$ and $k^w_{j'}$ for some $j$ and $j'$.

We use $W^b_G((k_i); u) = |W^b_G((k_i); u)|$ to denote the number of these balanced tours.

As with $W_G((h_i); u)$, $W^b_G((k_i); u)$ may be empty. Observe also that, since any tour on a forest is balanced, $W^b_F((2k_i); u) = W^b_F((k_i); u)$ for any forest $F$ and $u \in V(F)$. Moreover, for any graph $G$, we have $W^b_G((k_i); u) \leq W_G((2k_i); u)$, with equality if and only if the component of $G^+$ containing $u$, if present, is acyclic, where $G^+$ is the subgraph of $G$ induced by the edges that are actually traversed by tours in the family.

**Visits and excursions**

We use $\Psi(G, v)$ to denote the number of visits to $v$ of any tour on $G$ in some family (specified by the context). In practice, this notation is unambiguous because we only consider one family of tours on a particular graph at a time. Observe that any tour in $W_G((h_i); u)$ visits vertex $v \neq u$ exactly $\frac{1}{2}(h^v_1 + h^v_2 + \ldots + h^v_{d(v)})$ times, and that for balanced tours in $W^b_G((k_i); u)$ we have $\Psi(G, v) = k^v_1 + k^v_2 + \ldots + k^v_{d(v)}$.

If $\Psi(G, v)$ is positive, then separating the visits to $v$ are $\Psi(G, v) - 1$ “subtours” starting and ending at $v$; we refer to these subtours as excursions from $v$.

**Multinomial coefficients**

In our calculations, we make considerable use of multinomial coefficients, with their combinatorial interpretation, for which we use the standard notation

$$\binom{n}{k_1, k_2, \ldots, k_r} = \frac{n!}{k_1! k_2! \ldots k_r!}, \quad \text{where } \sum_{i=1}^{r} k_i = n,$$
to denote the number of ways of distributing \( n \) distinguishable objects between \( r \) (distinguishable) bins, such that bin \( i \) contains exactly \( k_i \) objects (\( 1 \leq i \leq r \)).

We make repeated use of the fact that a multinomial coefficient can be decomposed into a product of binomial coefficients as follows:
\[
\binom{n}{k_1, \ldots, k_r} = \binom{k_1}{k_1, k_2} \cdots \binom{k_r}{k_r}
\]
We consider a multinomial coefficient that has one or more negative terms to be zero. This guarantees that the monotonicity condition \( \binom{n}{k_1, \ldots, k_r} \leq \binom{n+1}{k_1, 1, \ldots, k_r} \) holds for all possible sets of values.

### 2.2 Tours on trees

We begin by establishing bounds on the size of families of tours on trees. As we noted above, all such tours are balanced. We start with star graphs, giving an exact enumeration of any family:

**Lemma 2.1.** If \( S_m \) is the star graph \( K_{1,m} \) with central vertex \( u \), then
\[
W_{S_m}^\bullet((k_i); u) = \binom{k_1 + k_2 + \ldots + k_m}{k_1, k_2, \ldots, k_m} = \binom{\Psi(S_m, u)}{k_1^u, k_2^u, \ldots, k_{d(u)}^u}.
\]

**Proof.** \( W_{S_m}^\bullet((k_i); u) \) consists of all possible interleavings of \( k_i \) excursions from \( u \) out-and-back along each \( e_i \).

It is possible to extend our exact enumeration to those families of balanced tours on trees in which every internal (non-leaf) vertex is visited at least once. These families are never empty.

**Lemma 2.2.** If \( T \) is a tree, \( u \in V(T) \) and, for each \( v \neq u \), \( e_v^u \) is the edge incident to \( v \) that is on the unique path between \( u \) and \( v \), and if \( k_v^u \) is positive for all internal vertices \( v \) of \( T \), then
\[
W_T^\bullet((k_i); u) = \binom{\Psi(T, u)}{k_1^u, k_2^u, \ldots, k_{d(u)}^u} \prod_{v \neq u} \binom{\Psi(T, v) - 1}{k_1^v - 1, k_2^v, \ldots, k_{d(v)}^v}.
\]

**Proof.** We use induction on the number of internal vertices. Note that the multinomial coefficient for a leaf vertex simply contributes a factor of 1 to the product. Lemma 2.1 provides the base case.

Given a tree \( T \) with \( m \) edges \( e_1, \ldots, e_m \), and a leaf \( v \) of \( T \), let \( T' \) be the tree “grown” from \( T \) by attaching \( r \) new pendant edges \( e_{m+1}, \ldots, e_{m+r} \) to \( v \).

If \( k_v^u \) is positive, since \( v \) is a leaf, each tour in \( W_T^\bullet((k_1, \ldots, k_m); u) \) visits \( v \) exactly \( k_v^u \) times, with \( k_v^u - 1 \) excursions from \( v \) along \( e_v^u \) separating these visits. Any such tour can be
extended to a tour in $W^B_T(k_1,\ldots,k_{m+r};u)$ by arbitrarily interleaving $k_{m+i}$ new excursions out-and-back along each new pendant edge $e_{m+i}$ ($i = 1, \ldots, r$) with the existing $k_i^v - 1$ excursions from $v$ along $e_i^v$.

This exact enumeration can be used to generate the following general bounds on the number of tours on trees:

**Corollary 2.3.** If $T$ is a tree, then for any vertex $u \in V(T)$, $W^B_T((k_i);u)$ satisfies the following bounds:

$$\prod_{v \in V(T)} \left( \frac{\Psi(T,v) - d(v)}{k_1^v - 1, k_2^v - 1, \ldots, k_{d(v)}^v - 1} \right) \leq W^B_T((k_i);u) \leq \prod_{v \in V(T)} \left( \frac{\Psi(T,v)}{k_1^v, k_2^v, \ldots, k_{d(v)}^v} \right).$$

**Proof.** If all the $k_i$ are positive, then this follows directly from Lemma 2.2.

If one or more of the $k_i$ is zero, then the lower bound is trivially true, because one of the multinomial coefficients is zero. The upper bound also holds trivially if there are no tours in the family. Otherwise, let $T^+$ be the subtree of $T$ induced by the vertices actually visited by tours in $W^B_T((k_i);u)$. Then $W^B_T((k_i);u) = W^B_{T^+}((k_i);u)$. But we know that

$$W^B_{T^+}((k_i);u) \leq \prod_{v \in V(T^+)} \left( \frac{\Psi(T^+,v)}{k_1^v, k_2^v, \ldots, k_{d(v)}^v} \right) = \prod_{v \in V(T)} \left( \frac{\Psi(T,v)}{k_1^v, k_2^v, \ldots, k_{d(v)}^v} \right)$$

as a result of Lemma 2.2 and the fact that $k_i^v = 0$ for all edges $e_i^v$ incident to unvisited vertices $v \in V(T) \setminus V(T^+)$. 

### 2.3 Treeification

In order to establish the lower and upper bounds for tours on arbitrary connected graphs, we relate tours on a connected graph $G$ to (balanced) tours on a related tree which we call a treeification of $G$. The process of treeification consists of repeatedly breaking cycles until the resulting graph is acyclic. This creates a sequence of graphs $G = G_0, G_1, \ldots, G_t = T$ where $T$ is a tree. We call this sequence a treeification sequence.

Formally, we define a treeification of a connected graph to be the result of the following (nondeterministic) process that transforms a connected graph into a tree with the same number of edges.
To treeify a connected graph $G = G_0$, we first give an (arbitrary) order to its vertices. Then we apply the following vertex-splitting operation in turn to each $G_j$ to create $G_{j+1}$ ($j = 0, 1, \ldots$), until no cycles remain:

1. Let $v$ be the first vertex (in the ordering) that occurs in some cycle $C$ of $G_j$.
2. Split vertex $v$ by doing the following (see Figure 3):
   
   (a) Delete an edge $xv$ from $E(C)$ (there are two choices for vertex $x$).
   (b) Add a new vertex $v'$ (to the end of the vertex ordering).
   (c) Add the pendant edge $xv'$ (making $v'$ a leaf).

![Figure 3: Splitting vertex $v$](image)

Note that if a vertex $v$ is split multiple times when treeifying a graph $G$, these splits occur contiguously (because of the ordering placed on the vertices of $G$). Thus, if $v$ is split $r$ times, there is a contiguous subsequence $G_j, G_{j+1}, \ldots, G_{j+r}$ of the treeification sequence that corresponds to the splitting of $v$. See Figure 4 for an example of a treeification sequence.

![Figure 4: A treeification sequence; numbers show the first few vertices in the ordering](image)

There is a natural way to establish a relationship between tours on different graphs in a treeification sequence $G_0, \ldots, G_t$. The treeification process induces graph homomorphisms (edge preserving maps) between the graphs in such a sequence. For all $i < j$, there is a surjective homomorphism from $G_j$ onto $G_i$. This homomorphism is also locally injective since it maps neighbourhoods of $G_j$ injectively into neighbourhoods of $G_i$. A locally injective map such as this is also known as a partial cover. In particular, for each $j < t$, there is a partial cover of $G_{j+1}$ onto $G_j$ that maps the new pendant edge $xv'$ to the edge $xv$ that it replaces. These homomorphisms impart a natural correspondence between families of tours on different graphs in the treeification sequence, which we will employ later to determine our bounds.
Although the concept of treeification is a very natural one, these particular “partial covering trees” do not appear to have been studied before; their only previous use seems to be by Yarkony, Fowlkes and Ihler to address a problem in computer vision [34]. For a general introduction to graph homomorphisms, see see the monograph by Hell and Nešetřil [15]. For more on partial maps and other locally constrained graph homomorphisms, see the survey article by Fiala and Kratochvíl [14].

If we have a treeification sequence \( G = G_0, \ldots, G_t = T \) for a connected graph \( G \), we can use a three-stage process to establish a lower or upper bound for a family of tours on \( G \). In the first stage (“splitting once”), we relate the number of tours in the family on \( G_j \) (\( j < t \)) to the number of tours in a related family on \( G_{j+1} \). In the second stage (“fully splitting one vertex”), for a vertex \( v \), we consider the subsequence \( G_j, \ldots, G_{j+r} \) that corresponds to the splitting of \( v \) and, iterating the inequality from the first stage, relate the number of tours on \( G_j \) to the number of tours on \( G_{j+r} \). Finally (“fully splitting all vertices”), iterating the inequality from the second stage, we relate the number of tours on \( G = G_0 \) to the number of tours on \( G_t = T \), and employ the bounds on tours on \( T \) from Corollary 2.3 to determine the bound for the family of tours on \( G \).

In Subsection 2.4, we use this three-stage process to produce a lower bound on \( W^b_G((k_i); u) \). Then, in Subsection 2.5, we use the same three-stage process to establish an upper bound on \( W_G((h_i); u) \).

### 2.4 The lower bound

Our lower bound is on the number of balanced tours. We only consider the families in which every edge is traversed at least once in each direction. On a connected graph, these families are never empty.

**Lemma 2.4.** If \( G \) is a connected graph with \( m \) edges and \( k_1, \ldots, k_m \) are all positive, then for any vertex \( u \in V(G) \),

\[
W^b_G(k_1, k_2, \ldots, k_m; u) \geq \prod_{v \in V(G)} \left( \frac{k_v^1 + k_v^2 + \ldots + k_d^v - d(v)}{k_v^1 - 1, k_v^2 - 1, \ldots, k_d^v - 1} \right).
\]

This lower bound does not hold in general for a disconnected graph since there are no tours possible if there is any positive \( k_i \) in a component not containing \( u \).

**Proof.** Let \( T \) be some treeification of \( G \) with treeification sequence \( G = G_0, \ldots, G_t = T \) in which vertex \( u \) is never split. (This is possible by positioning \( u \) last in the ordering on the vertices.)

By exhibiting a surjection from \( W^b_G((k_i); u) \) onto \( W^b_T((k_i); u) \) that is consistent with the homomorphism from \( T \) onto \( G \) induced by the treeification process, we determine an inequality relating the number of tours in the two families.
I. Splitting once

Our first stage is to associate a number of tours on \( G_j \), in \( W^a_{G_j}((k_i); u) \), to each tour on \( G_{j+1} \), in \( W^a_{G_{j+1}}((k_i); u) \).

To simplify the notation, let \( H_0 = G_j \) and \( H = G_{j+1} \) for some \( j < t \). Let \( v \) be the vertex of \( H_0 \) that is split in \( H \), and let \( v' \) be the leaf vertex in \( H \) added when splitting \( v \). Let \( e_1 \) be the (only) edge incident to \( v' \) in \( H \); we also use \( e_1 \) to refer to the corresponding edge (incident to \( v \)) in \( H_0 \) (see Figure 5).

\[ H = G_{j+1}: \quad \begin{array}{c} v' \\ k_1 \\ e_1 \end{array} \quad \rightarrow \quad H_0 = G_j: \quad \begin{array}{c} v \\ k_1 \\ e_1 \end{array} \]

**Figure 5:** Tours on \( H_0 \) corresponding to a tour on \( H \)

Any tour in \( W^a_{H}((k_i); u) \) visits vertex \( v \) exactly \( \Psi(H, v) \) times and visits vertex \( v' \) (along \( e_1 \)) \( k_1 \) times. The corresponding tour on \( H_0 \) visits \( v \) exactly \( \Psi(H_0, v) = \Psi(H, v) + k_1 \) times. Of these visits there are \( k_1 \) which arrive along \( e_1 \) and then depart along \( e_1 \).

Since \( \Psi(H_0, v) \) is positive, separating the visits are \( \Psi(H_0, v) - 1 \) excursions from \( v \). Depending on whether the final visit to \( v \) departs along \( e_1 \) or not, either \( k_1 - 1 \) or \( k_1 \) of these excursions begin with a traversal of \( e_1 \); these are interleaved with the other \( \Psi(H, v) \) or \( \Psi(H, v) - 1 \) excursions which begin with a traversal of some other edge.

Changing the interleaving of these two sets of excursions (without altering their internal ordering) produces at least

\[
\min \left[ \binom{\Psi(H_0, v) - 1}{k_1 - 1}, \binom{\Psi(H_0, v) - 1}{k_1} \right] \geq \binom{\Psi(H_0, v) - 2}{k_1 - 1}
\]

distinct tours in \( W^a_{H_0}((k_i); u) \).

Note that there is only one interleaving of the sets of excursions that corresponds to a valid tour in \( W^a_{H}((k_i); u) \): the one in which the excursions beginning with a traversal of \( e_1 \) away from \( v \) are arranged so they occur immediately following a traversal of \( e_1 \) towards \( v \).

Hence we can deduce that

\[
W^a_{H_0}((k_i); u) \geq \binom{\Psi(H_0, v) - 2}{k_1 - 1} W^a_H((k_i); u).
\] (1)
II. Fully splitting one vertex

For a given vertex $v$, let $H_0, H_1, \ldots, H_r$ be the subsequence of graphs that corresponds to the splitting of $v$. In our second stage, we relate the number of tours on $H_0$ to the number of tours on $H_r$.

Note that $\Psi(H_0, v) = \Psi(G, v)$ and $\Psi(H_r, v) = \Psi(T, v)$ since the splitting of other vertices cannot affect the number of visits to $v$.

Let $e_1, \ldots, e_r$ be the new pendant edges in $H_r$, and hence also in $T$, added when $v$ is split, and let $e_1, \ldots, e_r$ also denote the corresponding edges in $G$. Then $\Psi(H_{i-1}, v) = \Psi(H_i, v) + k_i$ for $1 \leq i \leq r$, and thus $\Psi(H_{i-1}, v) = \Psi(T, v) + k_i + k_{i+1} + \ldots + k_r$, and in particular $\Psi(G, v) = \Psi(T, v) + k_1 + \ldots + k_r$.

Hence, by iterating inequality (1),

$$W_{H_0}^b((k_i); u) \geq \prod_{i=1}^r \left( \frac{\Psi(H_{i-1}, v) - 2}{k_i - 1} \right) W_{H_r}^b((k_i); u)$$

$$= \prod_{i=1}^r \left( \frac{\Psi(T, v) + \left( \sum_{j=i}^r k_j \right) - 2}{k_i - 1} \right) W_{H_r}^b((k_i); u)$$

$$\geq \prod_{i=1}^r \left( \frac{\Psi(T, v) + \left( \sum_{j=i}^r (k_j - 1) \right) - 1}{k_i - 1} \right) W_{H_r}^b((k_i); u)$$

$$= \left( \frac{\Psi(G, v) - (r + 1)}{\Psi(T, v) - 1, k_1 - 1, k_2 - 1, \ldots, k_r - 1} \right) W_{H_r}^b((k_i); u).$$

(2)

III. Fully splitting all vertices

Finally, our third stage is to relate the number of tours on $G$ to the number of tours on $T$ and then apply the tree bounds to establish the required lower bound.

For each $v \in V(G)$, let $r(v)$ be the number of times $v$ is split. Note that $r(v)$ is less than the degree of $v$ in $G$ since $d_G(v) = d_T(v) + r(v)$.

Thus, with a suitable indexing of the edges around each vertex, if we iterate inequality (2)
and combine with the lower bound on $W_T^b((k_i); u)$ from Corollary 2.3, we get

$$W_G^b((k_i); u) \geq \prod_{v \in V(G)} \left( \frac{\Psi(G, v) - (r(v) + 1)}{\Psi(T, v) - 1, k_1^v - 1, \ldots, k_r^v - 1} \right) W_T^b((k_i); u)$$

$$\geq \prod_{v \in V(G)} \left( \frac{\Psi(G, v) - (r(v) + 1)}{\Psi(T, v) - 1, k_1^v - 1, \ldots, k_r^v - 1} \right) \left( \frac{\Psi(T, v) - d_T(v)}{k_1^{v+1} - 1, \ldots, k_{d_G(v)}^{v} - 1} \right)$$

$$\geq \prod_{v \in V(G)} \left( \frac{\Psi(G, v) - d_G(v)}{k_1^v - 1, k_2^v - 1, \ldots, k_{d_G(v)}^v - 1} \right)$$

concluding the proof of Lemma 2.4.

\[\square\]

### 2.5 The upper bound

Our upper bound applies to arbitrary families of tours $W_G((h_i); u)$, without any restriction on the values of the $h_i$. Subsequently, we will apply this result to families of tours of even length.

**Lemma 2.5.** If $G$ is a connected graph with $m$ edges and $u$ is any vertex of $G$, then

$$W_G(h_1, h_2, \ldots, h_m; u) \leq (h + 2m)^m \prod_{v \in V(G)} \left( \frac{k_1^v + k_2^v + \ldots + k_{d_G(v)}^v}{k_1^v, k_2^v, \ldots, k_{d_G(v)}^v} \right)$$

for some $k_i \in \left[ \frac{1}{2}h_i, \frac{1}{2}h_i + m \right]$ $(1 \leq i \leq m)$, where $h = h_1 + \ldots + h_m$ is the length of the tours in the family and $k_1^v, k_2^v, \ldots, k_{d_G(v)}^v$ are the $k_i$ corresponding to edges incident to $v$.

**Proof.** Let $T$ be some treeification of $G$ with treeification sequence $G = G_0, \ldots, G_t = T$ in which vertex $u$ is never split. (This is possible by positioning $u$ last in the ordering on the vertices.)

We relate the number of (arbitrary) tours in $W_G((h_i); u)$ to the number of (balanced) tours in $W_T^b((k_i); u)$, for some $k_i$ not much greater than $\frac{1}{2}h_i$. This is achieved by exhibiting a surjection from $W_T^b((k_i); u)$ onto $W_G((h_i); u)$ that is consistent with the homomorphism from $T$ onto $G$ induced by the treeification process.

The proof is broken down into the same three stages as for the proof of the lower bound. Initially, we restrict ourselves to the case in which all the $\Psi(G, v)$ are positive. The case of unvisited vertices is addressed in an additional stage at the end.
I. Splitting once

Our first stage is to associate to each tour on $G_j$ a number of tours on $G_{j+1}$. However, unlike in the proof of the lower bound, the relationship is not between classes with the same parameterisation. Rather, we relate tours in $\mathcal{W}_{G_j}((h_i);u)$ to slightly longer tours in $\mathcal{W}_{G_{j+1}}((h'_i);u)$, for some $h'_i$ such that, for each $i$, $h_i \leq h'_i \leq h_i + 2$.

As we did for the lower bound, let $H_0 = G_j$ and $H = G_{j+1}$ for some $j < t$. Let $v$ be the vertex of $H_0$ that is split in $H$, and let $v'$ be the leaf vertex in $H$ added when splitting $v$.

Again, let $e_1$ be the (only) edge incident to $v'$ in $H$; we also use $e_1$ to refer to the corresponding edge (incident to $v$) in $H_0$.

Let $C$ be some cycle in $H_0$ containing $e_1$, and let $e_2$ be the other edge on $C$ that is incident to $v$ (in both $H_0$ and $H$).

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{figure6.png}
\caption{Tours on $H$ corresponding to a tour on $H_0$; $k_1 = \lceil \frac{1}{2} h_1 \rceil + 1$}
\end{figure}

Given a tour on $H_0$, we want to modify it so that the result is a valid tour on $H$. For a tour on $H_0$ to be valid on $H$, each traversal of $e_1$ towards $v$ must be immediately followed by a traversal of $e_1$ from $v$. See Figure 6.

To achieve this, we make three kinds of changes to excursions from $v$:

1. Reverse the direction of some of the excursions.
2. Add one or two additional excursions (around $C$).
3. Modify the interleaving of excursions.

To manage the details, given a tour on $H_0$, we consider the $\Psi(H_0,v) - 1$ excursions from $v$ to be partitioned into subsets as follows:

- **-**: $a_0$ excursions that don’t traverse $e_1$ at all
- **-**: $a_1$ excursions that begin but don’t end with a traversal of $e_1$
- **-**: $a_2$ excursions that end but don’t begin with a traversal of $e_1$
- **-**: $a_3$ excursions that both begin and end with traversals of $e_1$

We also refer to 1-* and 1-1 excursions as 1-initial, and *-* and *-1 excursions as *-initial.

We refer to the edge traversed in arriving for the first visit to $v$ as the arrival edge and to the edge traversed in departing from the last visit to $v$ as the departure edge. We
call their traversals the **arrival** and the **departure** respectively. To account for these, we define \(a_1^+\) to be \(a_1 + 1\) if the departure edge is \(e_1\) and to be \(a_1\) otherwise, and define \(a_2^+\) to be \(a_2 + 1\) if the arrival edge is \(e_1\) and to be \(a_2\) otherwise.

So, to transform a tour on \(H_0\) into one on \(H\), we perform the following three steps:

1. If \(a_2^+ > a_1 + 1\), reverse the direction of the last \(\lfloor \frac{1}{2}(a_2^+ - a_1) \rfloor\) of the \(*-1\) excursions (making them \(1-\star\)).
   On the other hand, if \(a_2^+ < a_1\), reverse the direction of the last \(\lceil \frac{1}{2}(a_1 - a_2^+) \rceil\) of the \(1-\star\) excursions (making them \(*-1\)).
   Update the values of \(a_1\) and \(a_2\) to reflect these reversals; we now have \(a_2^+ = a_1\) or \(a_2^+ = a_1 + 1\).

2. If \(a_1^+ + a_2^+\) is even \((h_1\) is even\) or \(a_1^+ = a_1\) (the departure edge isn't \(e_1\)), add a new \(1-\star\) excursion consisting of a tour around the cycle \(C\) (returning to \(v\) along \(e_2\)); this should be added following all the existing excursions.
   Also, if \(a_1^+ + a_2^+\) is even \((h_1\) is even\) or \(a_1^+ = a_1 + 1\) (the departure edge is \(e_1\)), add a new \(*-1\) excursion consisting of a tour around the cycle \(C\) (departing from \(v\) along \(e_2\)); this should be added following all the existing excursions.
   Update the values of \(a_1\) and \(a_2\) to reflect the presence of the new excursion(s); we now have \(a_2^+ = a_1^+\).

3. Change the interleaving of the \(1\)-initial excursions with the \(*\)-initial excursions so that each visit to \(v\) along \(e_1\) returns immediately along \(e_1\). This is always possible (see below) and there is only one way of doing it. We now have a valid tour on \(H\).

<table>
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<tr>
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</tr>
</tbody>
</table>

**Figure 7**: Two examples of transforming tours by modifying excursions

Figure 7 shows two examples of this process. The two-digit entries in the table represent the initial and final edges traversed by excursions from \(v\); the single-digit entries give the arrival and departure edges; \(e_3\) is an additional edge incident to \(v\). \(1\)-initial excursions (whose interleaving with the \(*\)-initial excursions is modified by Step 3) are shown in bold. In Step 1, excursions which are reversed are shown in italics.
Validation of Step 3

If we consider the 1-initial excursions and the ∗-initial excursions as two separate lists, with the ∗-initial excursions (together with the arrival and departure) as “fixed”, then we can insert 1-initial excursions into the list of ∗-initial excursions as follows:

Following each ∗-1 excursion (and the arrival if it is along $e_1$), place the next unused 1-∗ excursion together with any unused 1-1 excursions that precede it.

This procedure is successful, and ensures that each visit to $v$ along $e_1$ returns immediately along $e_1$ as along as the number of traversals of $e_1$ towards $v$ equals the number of traversals of $e_1$ away from $v$, unless either

- the departure edge is not $e_1$ and the last 1-initial excursion is a 1-1 excursion (the minimal example being -2 1-1 2-, using the notation of Figure 7), or
- the departure edge is $e_1$ and the last ∗-initial excursion is a ∗-∗ excursion (the minimal example being -1 2-2 1-).

The rules controlling the addition of new final ∗-1 and 1-∗ excursions in Step 2 guarantee both that the number of traversals of $e_1$ towards $v$ is the same as the number of traversals of $e_1$ away from $v$, and also that neither of the two exceptional cases occur. Thus Step 3 is always valid.

Counting

Step 2 can add at most two additional excursions from $v$ (around $C$), so given a tour in $W_{H_0}((h_i); u)$, this process produces a tour in $W_H(2k_1, h_2', \ldots, h_m'; u)$ where $k_1 = \left\lfloor \frac{1}{2}h_1 \right\rfloor + 1$, and for each $i$, $h_i \leq h_i' \leq h_i + 2$.

After completing Step 1, there are $a_1 + a_2 + 1$ ways in which it could be undone (reverse no more than $a_1$ 1-* excursions, reverse no more than $a_2$ ∗-1 excursions, or do nothing). Since $h_1 = a_1 + a_2 + 2a_3$, this does not exceed $h_1 + 1$.

Also, after Step 3, there are either $k_1$ or $k_1 - 1$ excursions that begin with a traversal of $e_1$ that could, prior to the step, have been arbitrarily interleaved with those that don’t.

Thus we see that there are no more than

$$(h_1 + 1) \max \left[ \left( \frac{\Psi(H, v) + k_1 - 1}{k_1} \right), \left( \frac{\Psi(H, v) + k_1 - 1}{k_1 - 1} \right) \right] \leq 2k_1 \left( \frac{\Psi(H, v) + k_1}{k_1} \right)$$

distinct tours in $W_{H_0}((h_i); u)$ that generate any specific tour in $W_H(2k_1, h_2', \ldots, h_m'; u)$.

Hence,

$$W_{H_0}((h_i); u) \leq 2k_1 \left( \frac{\Psi(H, v) + k_1}{k_1} \right) W_H(2k_1, h_2', \ldots, h_m'; u). \quad (3)$$

16
Note also that either \( \Psi(H_0, v) = \Psi(H, v) + k_1 - 2 \) or \( \Psi(H_0, v) = \Psi(H, v) + k_1 - 1 \) (depending on whether \( h_1 \) is even or odd), and so

\[
\Psi(H_0, v) < \Psi(H, v) + k_1. \tag{4}
\]

Furthermore, \( \Psi(H, v) \) is positive, since the additional excursion(s) ensure that \( h_2' \) is positive.

II. Fully splitting one vertex

For a given vertex \( v \), let \( H_0, H_1, \ldots, H_r \) be the subsequence of graphs that corresponds to the splitting of \( v \). In the second stage of our proof, we relate the number of tours on \( H_0 \) to the number of tours on \( H_r \).

Note again that \( \Psi(H_0, v) = \Psi(G, v) \) and \( \Psi(H_r, v) = \Psi(T, v) \) since the splitting of other vertices cannot affect the number of visits to \( v \).

We assume that \( \Psi(G, v) \) is positive, and hence that \( \Psi(H_0, v), \ldots, \Psi(H_r, v) = \Psi(T, v) \) are all positive too.

Let \( e_1, \ldots, e_r \) be the new pendant edges in \( T \) added when \( v \) is split, and let \( e_1, \ldots, e_r \) also denote the corresponding edges in \( G \). Then, by (4), for some \( k_1, \ldots, k_r \) such that

\[
\frac{1}{2} h_i \leq k_i \leq \frac{1}{2} h_i + i,
\]

we have

\[
\Psi(H_{i-1}, v) < \Psi(H_i, v) + k_i,
\]

and thus

\[
\Psi(H_{i-1}, v) < \Psi(T, v) + k_i + \ldots + k_r.
\]

Hence, by iterating inequality (3), if \( h_i' = 2k_i \) for \( 1 \leq i \leq r \), then for some \( h_{r+1}', \ldots, h_m' \) such that \( h_i \leq h_i' \leq h_i + 2r \),

\[
W_{H_0}((h_i); u) \leq 2^r \left( \prod_{i=1}^{r} k_i \left( \Psi(H_i, v) + k_i \right) \right) W_{H_r}((h_i'); u)
\]

\[
< 2^r \left( \prod_{i=1}^{r} k_i \left( \Psi(T, v) + \sum_{j=i}^{r} k_j \right) \right) W_{H_r}((h_i'); u)
\]

\[
= 2^r \left( \prod_{i=1}^{r} k_i \right) \left( \Psi(T, v) + \sum_{i=1}^{r} k_i \right) W_{H_r}((h_i'); u). \tag{5}
\]

III. Fully splitting all vertices

In the third stage of the proof, we relate the number of tours on \( G \) to the number of tours on \( T \) and then apply the tree bounds to establish the required upper bound for the case in which all the \( \Psi(G, v) \) are positive.
For each $v \in V(G)$, let $r(v)$ be the number of times $v$ is split. Also, let $h = h_1 + \ldots + h_m$ be the length of the tours in $W_G((h_i); u)$.

Thus, with a suitable indexing of the edges around each vertex, if we iterate inequality (5) and combine with the upper bound on $W_T^B((k_i); u)$ from Corollary 2.3, we get, for some $k_1, \ldots, k_m$ such that $1/2 h_i \leq k_i \leq 1/2 h_i + m$,

$$W_G((h_i); u) \leq 2^m \left( \prod_{i=1}^{m} k_i \right) \prod_{v \in V(G)} \left( \Psi(T, v) + \sum_{i=1}^{r(v)} k_i^v \right) W_T^B((k_i); u)$$

$$\leq (h + 2m)^m \prod_{v \in V(G)} \left( \Psi(T, v) + \sum_{i=1}^{r(v)} k_i^v \right) \left( \Psi(T, v), k_1^v, \ldots, k_{r(v)}^v \right)$$

$$= (h + 2m)^m \prod_{v \in V(G)} \left( k_1^v + \ldots + k_{d(v)}^v \right),$$

using the fact that for each $i$, we have $k_i \leq 1/2 h + m$.

### IV. Unvisited vertices

Thus we have the desired result for the case in which all the $\Psi(G, v)$ are positive. To complete the proof, we consider families of tours in which some of the vertices are not visited.

If not all the $\Psi(G, v)$ are positive, then let $G^+$ be the subgraph of $G$ induced by the vertices actually visited by tours in $W_G((h_i); u)$. Then $W_G((h_i); u) = W_{G^+}((h_i); u)$. But we know that

$$W_{G^+}((h_i); u) \leq (h + 2m)^m \prod_{v \in V(G^+)} \left( k_1^v + \ldots + k_{d(v)}^v \right)$$

$$\leq (h + 2m)^m \prod_{v \in V(G)} \left( k_1^v + \ldots + k_{d(v)}^v \right)$$

because the inclusion of the unvisited vertices in $V(G) \setminus V(G^+)$ cannot decrease the value of the product. So the bound holds for any family $W_G((h_i); u)$.

This concludes the proof of Lemma 2.5.

### 2.6 Tours of even length

In this subsection, we consider the family of all tours of even length on a graph and prove that it grows at the same rate as the more restricted family of all balanced tours.
To do this, we make use of the fact that the growth rate of a collection of objects does not change if we make “small” changes to what we are counting. This follows directly from the definition of the growth rate. We will also use this observation when we consider the relationship between permutation grid classes and families of tours on graphs in the next section.

**Observation 2.6.** If \( S \) is a collection of objects, containing \( S_k \) objects of each size \( k \), that has a finite growth rate, then for any positive polynomial \( P \) and fixed non-negative integers \( d_1, d_2 \) with \( d_1 \leq d_2 \),

\[
\lim_{k \to \infty} \left( P(k) \sum_{j = k + d_1}^{k + d_2} S_j \right)^{1/k} = \lim_{k \to \infty} S_k^{1/k} = \text{gr}(S).
\]

We can employ our upper bound for \( W_G((h_i); u) \) to give us an upper bound for tours of a specific even length. We use \( W_G(h; u) \) to denote the number of tours of length \( h \) starting and ending at vertex \( u \).

**Lemma 2.7.** If \( G \) is a connected graph with \( m \) edges and \( u \) is any vertex of \( G \), then the number of tours of length \( 2k \) on \( G \) starting and ending at vertex \( u \) is bounded above as follows:

\[
W_G(2k; u) \leq (m + 1)^m (2k + 2m)^m \sum_{j = k + d_1}^{k + d_2} \prod_{v \in V(G)} \left( k_1^v + \ldots + k_{d(v)}^v \right).
\]

**Proof.** From Lemma 2.5, for any vertex \( u \) of a graph \( G \) with \( m \) edges, we know that

\[
W_G(2k; u) = \sum_{h_1 + \ldots + h_m = 2k} W_G((h_i); u) \leq (2k + 2m)^m \sum_{h_1 + \ldots + h_m = 2k} \prod_{v \in V(G)} \left( k_1^v + k_2^v + \ldots + k_{d(v)}^v \right)
\]

where each \( k_i \) is dependent on the sequence \((h_i)\) with \( \frac{1}{2}h_i \leq k_i \leq \frac{1}{2}h_i + m \).

There are no more than \((m + 1)^m\) different values of the \( h_i \) that give rise to any specific set of \( k_i \), and we have \( k \leq k_1 + \ldots + k_m \leq k + m^2 \), so

\[
W_G(2k; u) \leq (m + 1)^m (2k + 2m)^m \sum_{j = k}^{k + m^2} \sum_{k_1 + \ldots + k_m = j} \prod_{v \in V(G)} \left( k_1^v + \ldots + k_{d(v)}^v \right). \quad \Box
\]

Now, drawing together our upper and lower bounds enables us to deduce that the family of balanced tours on a graph \( G \) grows at the same rate as the family of all tours of even length on \( G \). We use \( \mathcal{W}_G^b \) for the family of all balanced tours on \( G \) and \( \mathcal{W}_G^e \) for the family of all tours of even length on \( G \), where, in both cases, we consider the size of a tour to be half its length.
Theorem 2.8. The growth rate of the family of balanced tours \( \mathcal{W}_G^B \) on a connected graph is the same as growth rate of the family of all tours of even length \( \mathcal{W}_G^E \) on the graph.

Proof. From Lemma 2.4, we know that
\[
\prod_{v \in V(G)} \left( k_v^1 + \ldots + k_v^{d(v)} \right) \leq W_G^B(k_1+1, \ldots, k_m+1; u).
\]
Substitution in the inequality in the statement of Lemma 2.7 then yields the following relationship between families of even-length and balanced tours:
\[
W_G(2k; u) \leq (m+1)^m (2k+2m)^m \sum_{j=k+m}^{k+m+m^2} W_G^B(j; u)
\]
where \( W_G^B(j; u) \) is the number of balanced tours of length \( 2j \) on \( G \) starting and ending at \( u \). Combining this with Observation 2.6 and the fact that \( W_G^B(k; u) \leq W_G(2k; u) \) produces the result \( \text{gr}(\mathcal{W}_G^B) = \text{gr}(\mathcal{W}_G^E) \).

Finally, before moving on to the relationship with permutation grid classes, we determine the value of the growth rate of the family of even-length tours \( \mathcal{W}_G^E \). This requires only elementary algebraic graph theory. We recall here the relevant concepts. The adjacency matrix, \( A = A(G) \) of a graph \( G \) has rows and columns indexed by the vertices of \( G \), with \( A_{i,j} = 1 \) or \( A_{i,j} = 0 \) according to whether vertices \( i \) and \( j \) are adjacent (joined by an edge) or not. The spectral radius \( \rho(G) \) of a graph \( G \) is the largest eigenvalue (which is real and positive) of its adjacency matrix.

Lemma 2.9. The growth rate of \( \mathcal{W}_G^E \) exists and is equal to the square of the spectral radius of \( G \).

Proof. If \( G \) has \( n \) vertices, then
\[
W_G(2k) = \sum_{u \in V(G)} W_G(2k; u) = \text{tr}(A(G)^{2k}) = \sum_{i=1}^{n} \lambda_i^{2k},
\]
where the \( \lambda_i \) are the (real) eigenvalues of \( A(G) \), the adjacency matrix of \( G \), since the diagonal entries of \( A(G)^{2k} \) count the number of tours of length \( 2k \) starting at each vertex. Thus,
\[
\text{gr}(\mathcal{W}_G^E) = \lim_{k \to \infty} \left( \sum_{i=1}^{n} \lambda_i^{2k} \right)^{1/k}
\]
Now the spectral radius is given by \( \rho = \rho(G) = \max_{1 \leq i \leq n} \lambda_i \), so we can conclude that
\[
\rho^2 = \lim_{k \to \infty} \left( \rho^{2k} \right)^{1/k} \leq \lim_{k \to \infty} \left( \sum_{i=1}^{n} \lambda_i^{2k} \right)^{1/k} \leq \lim_{k \to \infty} \left( (n\rho)^{2k} \right)^{1/k} = \rho^2.
\]
Thus, \( \text{gr}(\mathcal{W}_G^E) = \rho(G)^2 \). \( \Box \)
3 Grid classes

In this section, we prove our main theorem, that the growth rate of a monotone grid class of permutations is equal to the square of the spectral radius of its row-column graph.

The proof is as follows: First, we present an explicit expression for the number of gridded permutations of a given length. Then, we use this to show that the class of gridded permutations grows at the same rate as the family of tours of even length on its row-column graph. Finally, we demonstrate that the growth rate of a grid class is the same as the growth rate of the corresponding class of gridded permutations.

Let us begin by formally introducing the relevant permutation grid class concepts.

3.1 Notation and definitions

When defining grid classes, to match the way we view permutations graphically, we index matrices from the lower left corner, with the order of the indices reversed from the normal convention. For example, \( M_{2,1} \) is the entry in the second column from the left in the bottom row of \( M \).

\[
\begin{pmatrix}
\cdot & \cdot & \cdot \\
\cdot & \cdot & \cdot \\
\cdot & \cdot & \cdot \\
\cdot & \cdot & \cdot \\
\end{pmatrix}
\]

Figure 8: A gridding of permutation 31567482 in

If \( M \) is a 0/±1 matrix with \( t \) columns and \( u \) rows, then an \( M \)-gridding of a permutation \( \sigma \) of length \( k \) is a pair of sequences \( \frac{1}{2} = c_0 \leq c_1 \leq \ldots \leq c_t = k + \frac{1}{2} \) (the column dividers) and \( \frac{1}{2} = r_0 \leq r_1 \leq \ldots \leq r_u = k + \frac{1}{2} \) (the row dividers) such that for all \( i \in \{0, \ldots, t\} \) and \( j \in \{0, \ldots, u\} \), \( c_i - \frac{1}{2} \in \{0, \ldots, k\} \) and \( r_j - \frac{1}{2} \in \{0, \ldots, k\} \) and the subsequence of \( \sigma \) with indices between \( c_{i-1} \) and \( c_i \) and values between \( r_{j-1} \) and \( r_j \) is increasing if \( M_{i,j} = 1 \), decreasing if \( M_{i,j} = -1 \), and empty if \( M_{i,j} = 0 \). For example, in Figure 8, \( c_1 = \frac{11}{2} \) and \( r_1 = \frac{5}{2} \).

The grid class \( \text{Grid}(M) \) is then defined to be the set of all permutations that have an \( M \)-gridding. The griddings of a permutation in \( \text{Grid}(M) \) are its \( M \)-griddings. We say that \( \text{Grid}(M) \) has size \( m \) if its matrix \( M \) has \( m \) non-zero entries.

The concept of a grid class of permutations has been generalised, permitting arbitrary permutation classes in each cell (see Vatter [30]). We only consider monotone grid classes in this paper, which we simply call “grid classes”. An interactive demonstration of grid classes is available online [8].
Sometimes we need to consider a permutation along with a specific gridding. In this case, we refer to a permutation together with an $M$-gridding as an $M$-gridded permutation. We use Grid$^#(M)$ to denote the class of all $M$-gridded permutations, every permutation in Grid$(M)$ being present once with each of its griddings. We use Grid$^#_k(M)$ for the set of $M$-gridded permutations of length $k$.

**Row-column graphs**

If $M$ has $t$ rows and $u$ columns, the **row-column graph**, $G(M)$, of Grid$(M)$ is the bipartite graph with vertices $r_1, \ldots, r_t, c_1, \ldots, c_u$ and an edge between $r_i$ and $c_j$ if and only if $M_{i,j} \neq 0$ (see Figure 9 for an example). Note that any bipartite graph is the row-column graph of some grid class, and that the size (number of edges) of the row-column graph is the same as the size (number of non-zero cells) of the grid class.

![Figure 9: A grid class and its row-column graph](image)

The row-column graph of a grid class captures a good deal of structural information about the class, so it is common to apportion properties of the row-column graph directly to the grid class itself, for example speaking of a connected, acyclic or unicyclic grid class rather than of a grid class whose row-column graph is connected, acyclic or unicyclic. We follow this convention.

### 3.2 Counting gridded permutations

It is possible to give an explicit expression for the number of gridded permutations of length $k$ in any specified grid class. Observe the similarity to the formulae for numbers of tours.

**Lemma 3.1.** If $G = G(M)$ is the row-column graph of Grid$(M)$, where $G$ has $m$ edges $e_1, \ldots, e_m$, then the number of gridded permutations of length $k$ in Grid$^#_k(M)$ is given by

$$|\text{Grid}^#_k(M)| = \sum_{k_1 + \ldots + k_m = k} \prod_{v \in V(G)} \left( \binom{k_v^v}{ \sum \binom{k_v^v}{k_1^v, k_2^v, \ldots, k_d(v)} } \right)$$

where $k_1^v, k_2^v, \ldots, k_d(v)$ are the $k_i$ corresponding to edges incident to $v$ in $G$.  

22
Proof. A gridded permutation in Grid\#(M) consists of a number of points in each of the cells that correspond to a non-zero entry of M. For every permutation, the relative ordering of points (increasing or decreasing) within a particular cell is fixed by the value of the corresponding matrix entry. However, the relative interleaving between points in distinct cells in the same row or column can be chosen arbitrarily and independently for each row and column.

Now, each vertex in G corresponds to a row or column in M, with an incident edge for each non-zero entry in that row or column. Thus, the number of gridded permutations with \( k_i \) points in the cell corresponding to edge \( e_i \) for each \( i \) is given by the following product of multinomial coefficients:

\[
\prod_{v \in V(G)} \binom{k_1^v + k_2^v + \ldots + k_{d(v)}^v}{k_1^v, k_2^v, \ldots, k_{d(v)}^v}.
\]

The result follows by summing over values of \( k_i \) that sum to \( k \). \( \square \)

As an immediate consequence, we have the fact that the enumeration of a class of gridded permutations depends only on its row-column graph:

**Corollary 3.2.** If \( G(M) = G(M') \), then Grid\#(M) = Grid\#(M') for all \( k \).

### 3.3 Gridded permutations and tours

We now use Lemmas 2.4 and 2.7 to relate the number of gridded permutations of length \( k \) in Grid\#(M) to the number of tours of length \( 2k \) on \( G(M) \). We restrict ourselves to permutation classes with connected row-column graphs.

**Lemma 3.3.** If \( G(M) \) is connected, the growth rate of Grid\#(M) exists and is equal to the growth rate of \( W_{G(M)}^k \).

**Proof.** If matrix \( M \) has \( m \) non-zero entries (and thus \( G(M) \) has \( m \) edges), then for any vertex \( u \) of \( G(M) \), combining Lemmas 3.1 and 2.4, gives us

\[
|\text{Grid}\#_k(M)| \leq \sum_{k_1 + \ldots + k_m = k} W_{G(M)}^\#(k_1 + 1, k_2 + 1, \ldots, k_m + 1; u)
\]

\[
\leq \sum_{k_1 + \ldots + k_m = k} W_{G(M)}(2k_1 + 2, 2k_2 + 2, \ldots, 2k_m + 2; u)
\]

\[
\leq W_{G(M)}(2k + 2m).
\] (6)
On the other hand, from Lemma 2.7, for any vertex \( u \) of a graph \( G \) with \( m \) edges,

\[
W_G(2k; u) \leq (m + 1)^m (2k + 2m)^m \sum_{j=1}^{k+m^2} \prod_{v \in V(G)} \left( k_1^u + \ldots + k_d^u \right).
\]

Let \( W_G(h) \) be the number of tours of length \( h \) on \( G \) (starting at any vertex).

Now \( W_G(h) = \sum_{u \in V(G)} W_G(h; u) \), so, using Lemma 3.1, if \( G(M) \) has \( n \) vertices and \( m \) edges, we have

\[
W_G(M)(2k) \leq n (m + 1)^m (2k + 2m)^m \sum_{j=1}^{k+m^2} |\text{Grid}\#_j(M)|.
\]

The multiplier on the right side of this inequality is a polynomial in \( k \). Hence, using inequality (6) and Observation 2.6, we can conclude that

\[
gr(\text{Grid}\#(M)) = gr(W_G^k(M))
\]

if \( G(M) \) is connected.

\[\square\]

### 3.4 Counting permutations

We nearly have the result we want. The final link is the following lemma of Vatter which tells us that, as far as growth rates are concerned, classes of gridded permutations are indistinguishable from their grid classes.

**Lemma 3.4** (Vatter [30] Proposition 2.1). *The growth rate of a monotone grid class Grid\((M)\) exists and is equal to the growth rate of the corresponding class of gridded permutations Grid\#\( (M)\).*

**Proof.** Suppose that \( M \) has dimensions \( r \times s \). Every permutation in \( \text{Grid}(M) \) has at least one gridding in \( \text{Grid}\#(M) \), but no permutation in \( \text{Grid}(M) \) of length \( k \) can have more than \( P(k) = \binom{k+r-1}{r-1} \binom{k+s-1}{s-1} \) gridings in \( \text{Grid}\#(M) \) because \( P(k) \) is the number of possible choices for the row and column dividers (see Subsection 3.1). Since \( P(k) \) is a polynomial in \( k \), the result follows from Observation 2.6.

Thus, by Corollary 3.2:

**Corollary 3.5.** *Monotone grid classes with the same row-column graph have the same growth rate.*

24
3.5 The growth rate of grid classes

We now have all we need for the proof of our main theorem.

**Theorem 3.6.** The growth rate of a monotone grid class of permutations exists and is equal to the square of the spectral radius of its row-column graph.

**Proof.** For connected grid classes, the result follows immediately from Lemmas 2.9, 3.3 and 3.4. A little more work is required to handle the disconnected case.

If \( G(M) \) is disconnected, then the growth rate of \( \text{Grid}(M) \) is the maximum of the growth rates of the grid classes corresponding to the connected components of \( G(M) \) (see Proposition 2.10 in Vatter [30]).

Similarly, the spectrum of a disconnected graph is the union (with multiplicities) of the spectra of the graph’s components (see Theorem 2.1.1 in Cvetković, Rowlinson and Simić [13]). Thus the spectral radius of a disconnected graph is the maximum of the spectral radii of its components.

Combining these facts with Lemmas 2.9, 3.3 and 3.4 yields

\[
\text{gr}(\text{Grid}(M)) = \rho(G(M))^2
\]

as required. \( \square \)

4 Implications

As a consequence of Theorem 3.6, results concerning the spectral radius of graphs can be translated into facts about the growth rates of permutation grid classes. So we now present a number of corollaries that follow from spectral graph theoretic considerations.

The two recent monographs by Cvetković, Rowlinson and Simić [13] and Brouwer and Haemers [11] provide a valuable overview of spectral graph theory, so, where appropriate, we cite the relevant sections of these (along with the original reference for a result).

As a result of Corollary 3.5, changing the sign of non-zero entries in matrix \( M \) has no effect on the growth rate of \( \text{Grid}(M) \). For this reason, when considering particular collections of grid classes below, we choose to represent them by grid diagrams in which non-zero matrix entries are represented by a \( \bullet \). As with grid classes, we freely apportion properties of a row-column graph to corresponding grid diagrams.

Since transposing a matrix or permuting its rows and columns does not change the row-column graph of its grid class, there may be a number of distinct grid diagrams corresponding to a specific row-column graph (see Figure 10 for an example).
In many cases, we illustrate a result by showing a row-column graph and a corresponding grid diagram. We display just one of the possible grid diagrams corresponding to the row-column graph.

Our first result is the following elementary observation, which specifies a limitation on which numbers can be grid class growth rates. This is a consequence of the fact that the spectral radius of a graph is a root of the characteristic polynomial of an integer matrix.

**Corollary 4.1.** The growth rate of a monotone grid class is an algebraic integer (the root of a monic polynomial).

### 4.1 Slowly growing grid classes

Using results concerning graphs with small spectral radius, we can characterise grid classes with growth rates no greater than \( \frac{9}{2} \). This is similar to Vatter’s characterisation of “small” permutation classes (with growth rate less than \( \kappa \approx 2.20557 \)) in [30].

First, we recall that the growth rate of a disconnected grid class is the maximum of the growth rates of its components (see the proof of Theorem 3.6), so we only need to consider connected grid classes.

The connected graphs with spectral radius 2 are known as the Smith graphs. These are precisely the cycle graphs, the \( H \) graphs (paths with two pendant edges attached to both endvertices, including the star graph \( K_{1,4} \)), and the three other graphs shown in Figure 11. Similarly, the connected proper subgraphs of the Smith graphs are precisely the path graphs, the \( Y \) graphs (paths with two pendant edges attached to one endvertex) and the three other graphs in Figure 12. For details, see Smith [27] and Lemmens and Seidel [20]; also see [13] Theorem 3.11.1 and [11] Theorem 3.1.3.

With these, we can characterise all grid classes with growth rate no greater than 4:

\[ \frac{26}{25} \]
Corollary 4.2. If the growth rate of a connected monotone grid class equals 4, then its row-column graph is a Smith graph. If the growth rate of a connected monotone grid class is less than 4, then its row-column graph is a connected proper subgraph of a Smith graph. In particular, we have the following:

Corollary 4.3. A monotone grid class of any size whose row-column graph is a cycle or an H graph has growth rate 4.

In Appendix A of [30], Vatter considers staircase grid classes, whose row-column graphs are paths (see the leftmost grid diagram in Figure 12). The spectral radius of a path graph has long been known (Lovász and Pelikán [21]; also see [13] Theorem 8.1.17 and [11] 1.4.4), from which we can conclude:

Corollary 4.4. A monotone grid class of size \( m \) (having \( m \) non-zero cells) whose row-column graph is a path has growth rate \( 4 \cos^2 \left( \frac{\pi}{m+2} \right) \). This is minimal for any connected grid class of size \( m \).

A Y graph of size \( m \) has spectral radius \( 2 \cos \left( \frac{\pi}{2m} \right) \), and the spectral radii of the three other graphs at the right of Figure 12 are \( 2 \cos \left( \frac{\pi}{12} \right) \), \( 2 \cos \left( \frac{\pi}{18} \right) \), and \( 2 \cos \left( \frac{\pi}{30} \right) \), from left to right (see [11] 3.1.1). Thus we have the following characterisation of growth rates less than 4:

Corollary 4.5. If the growth rate of a monotone grid class is less than 4, it is equal to \( 4 \cos^2 \left( \frac{\pi}{k} \right) \) for some \( k \geq 3 \).

The only grid class growth rates no greater than 3 are 1, 2, \( \frac{1}{2} (3 + \sqrt{5}) \approx 2.618 \), and 3.

**Figure 12:** A path, a Y graph and the three other connected proper subgraphs of Smith graphs, with corresponding grid diagrams

**Figure 13:** E and F graphs

In order to characterise grid classes with growth rates slightly greater than 4, let an E graph be a tree consisting of three paths having one endvertex in common, and an F graph
be a tree consisting of a path with a pendant edge attached to each of two distinct internal vertices (see Figure 13). Then, results of Brouwer and Neumaier [10] and Cvetković, Doob and Gutman [12] imply the following (also see [13] Theorem 3.11.2):

**Corollary 4.6.** If a connected monotone grid class has growth rate between 4 and $2 + \sqrt{5}$, then its row-column graph is an $E$ or $F$ graph.

Thus, since $\sqrt{2 + \sqrt{5}}$ cannot be an eigenvalue of any graph (see [13] p. 93), we can deduce the following:

**Corollary 4.7.** If a monotone grid class properly contains a cycle then its growth rate exceeds $2 + \sqrt{5}$.

More recently, Woo and Neumaier [33] have investigated the structure of graphs with spectral radius no greater than $\frac{3}{2}\sqrt{2}$ (also see [13] Theorem 3.11.3). As a consequence, we have the following:

**Corollary 4.8.** If the growth rate of a connected monotone grid class is no greater than $\frac{9}{2}$, then its row-column graph is one of the following:

(a) a tree of maximum degree 3 such that all vertices of degree 3 lie on a path,

(b) a unicyclic graph of maximum degree 3 such that all vertices of degree 3 lie on the cycle, or

(c) a tree consisting of a path with three pendant edges attached to one endvertex.

### 4.2 Accumulation points of grid class growth rates

Using graph theoretic results of Hoffman and Shearer, it is possible to characterise all accumulation points of grid class growth rates.

As we have seen, the growth rates of grid classes whose row-column graphs are paths and $Y$ graphs grow to 4 from below; 4 is the least accumulation point of growth rates. The following characterises all accumulation points below $2 + \sqrt{5}$ (see Hoffman [16]):

**Corollary 4.9.** For $k = 1, 2, \ldots$, let $\beta_k$ be the positive root of

$$P_k(x) = x^{k+1} - (1 + x + x^2 + \ldots + x^{k-1})$$

and let $\gamma_k = 2 + \beta_k + \beta_k^{-1}$. Then $4 = \gamma_1 < \gamma_2 < \ldots$ are all the accumulation points of growth rates of monotone grid classes smaller than $2 + \sqrt{5}$.

The approximate values of the first eight accumulation points are: 4, 4.07960, 4.14790, 4.18598, 4.20703, 4.21893, 4.22582, 4.22988.

At $2 + \sqrt{5}$, things change dramatically; from this value upwards grid class growth rates are dense (see Shearer [24]):

28
Corollary 4.10. Every $\gamma \geq 2 + \sqrt{5}$ is an accumulation point of growth rates of monotone grid classes.

Figure 14: A grid diagram whose growth rate differs from $2\pi$ by less than $10^{-7}$, and its caterpillar row-column graph

Thus, for every $\gamma \geq 2 + \sqrt{5} \approx 4.236068$, there is a grid class with growth rate arbitrarily close to $\gamma$. Indeed, for $\gamma > 2 + \sqrt{5}$, Shearer’s proof provides an iterative process for generating a sequence of grid classes, each with a row-column graph that is a caterpillar (a tree such that all vertices of degree 2 or more lie on a path), with growth rates converging to $\gamma$ from below. An example is shown in Figure 14.

4.3 Increasing the size of a grid class

We now consider the effect on the growth rate of making small changes to a grid class.

Firstly, growth rates of connected grid classes satisfy a strict monotonicity condition (see [13] Proposition 1.3.10):

Corollary 4.11. Adding a non-zero cell to a connected monotone grid class while preserving connectivity increases its growth rate.

On the other hand, particularly surprising is the fact that grid classes with longer internal paths or cycles have lower growth rates.

An edge $e$ of $G$ is said to lie on an endpath of $G$ if $G - e$ is disconnected and one of its components is a (possibly trivial) path. An edge that does not lie on an endpath is said to be internal. Note that a graph has an internal edge if and only if it contains either a cycle or non-star $H$ graph.

An early result of Hoffman and Smith [17] shows that the subdivision of an internal edge reduces the spectral radius (also see [11] Proposition 3.1.4 and [13] Theorem 8.1.12). Hence, we can deduce the following unexpected consequence for grid classes:
Corollary 4.12. If $\text{Grid}(M)$ is connected, and $G(M')$ is obtained from $G(M)$ by subdividing an internal edge, then $\text{gr}(\text{Grid}(M')) < \text{gr}(\text{Grid}(M))$ unless $G(M)$ is a cycle or an $H$ graph.

For an example, see Figure 15.

4.4 Grid classes with extremal growth rates

Finally, we briefly consider grid classes with maximal or minimal growth rates for their size.

We call a grid class of a $1 \times m$ matrix a skinny grid class. The row-column graph of a skinny grid class is a star (see Figure 16). Stars have maximal spectral radius among trees (see [13] Theorem 8.1.17). This yields:

Corollary 4.13. Among all connected acyclic monotone grid classes of size $m$, the skinny grid classes have the largest growth rate (equal to $m$).

We have already seen (Corollary 4.4) that the connected grid classes with smallest growth rates are those whose row-column graph is a path. For unicyclic grid classes, we have the following (see [13] Theorem 8.1.18):

Corollary 4.14. Among all connected unicyclic monotone grid classes of size $m$, those whose row-column graph is a single cycle of length $m$ have the smallest growth rate (equal to 4).

There are many additional results known concerning graphs with extremal values for their spectral radii, especially for graphs with a small number of cycles. For an example, see the two papers by Simić [25, 26] on the largest eigenvalues of unicyclic and bicyclic graphs. Results like these can be translated into further facts concerning the growth rates of grid classes.
5 Concluding remarks

In light of Theorem 3.6, it seems likely to be worthwhile investigating whether there are other links between spectral graph theory and permutation grid classes, or indeed permutation classes in general. Specifically, are there properties of grid classes which are associated with other eigenvalues of the adjacency or Laplacian matrices of the row-column graph? And can algebraic graph theory be used to help determine the growth rate of an arbitrary permutation class (e.g. specified by its basis)?

Closely related to grid classes are geometric grid classes, as investigated by Albert, Atkinson, Bouvel, Ruškuc and Vatter [4]. The geometric grid class Geom(M) is a subset of Grid(M), permutations in Geom(M) satisfying an additional “geometric” constraint. Recently, the present author [9] has proved a result similar to Theorem 3.6 for the growth rates of geometric grid classes. Specifically, the growth rate of geometric grid class Geom(M) exists and is equal to the square of the largest root of the matching polynomial of the row-column graph of what is known as the “double refinement” of matrix M. This value coincides with \( \rho(G(M))^2 \) for acyclic classes, Geom(M) and Grid(M) being identical when \( G(M) \) is a forest.

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